## ITP 30002 Operating System

**Process** 

OSTEP Chapters 4 & 6

Shin Hong

## Motivation



Process

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### **Process**

- a running instance of a program
  - program vs. process
  - a kernel object that contains all information and resources given to the running instance
    - identified by a unique number (process ID)
- time-sharing of a CPU provides the illusion of many CPUs
  - concurrency vs. parallelism
  - mechanism: context switching
  - policies: scheduling

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## Constitution of Program Execution Context

- memory states
  - address space
- CPU states
  - registers: general-purpose and special-purpose
- I/O information

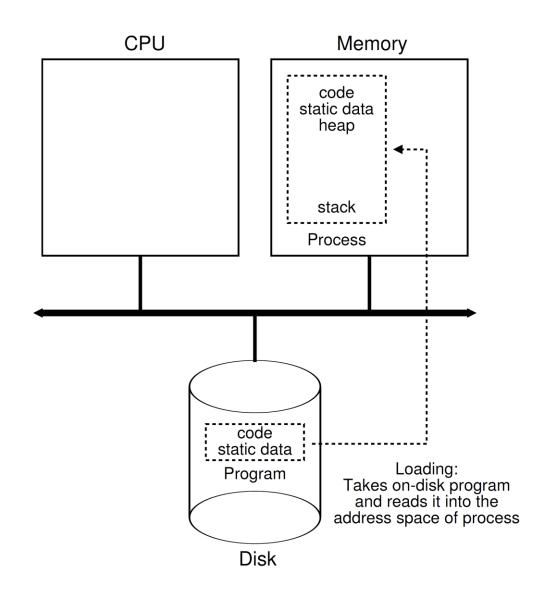
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# Life Cycle of a Process

- process creation
  - resource allocation
  - loading
    - eager manner
    - lazy manner



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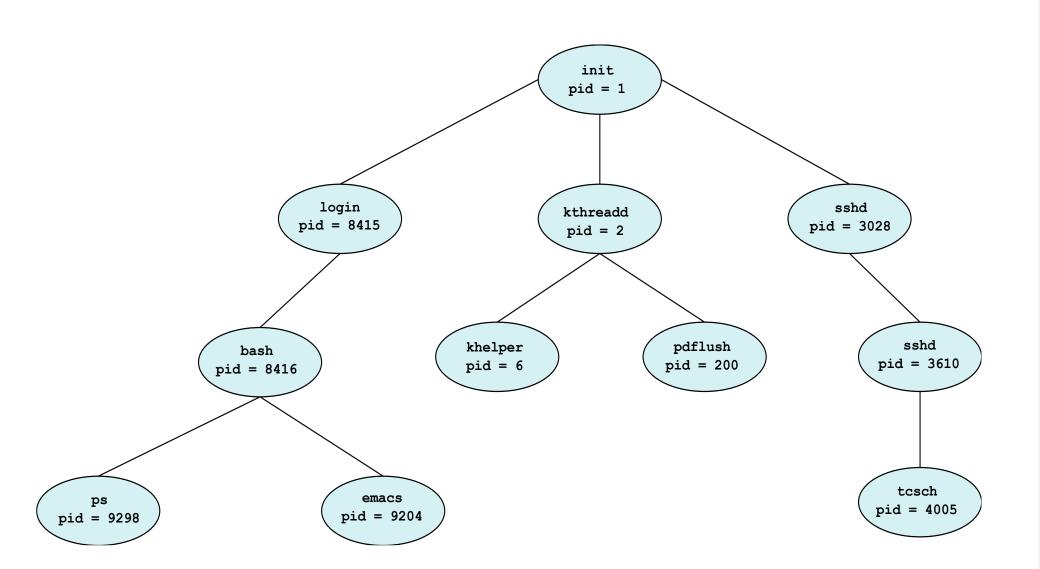
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### **Process Creation**

- A process is identified and managed via a process identifier (pid)
- A parent process can spawn a child process to delegate a subtask
  - A process can spawn multiple children processes
  - A parent process can run concurrently with its children processes
  - A child process, in turn create other processes, forming a tree of processes
  - A parent can wait until a child (or children) terminates
- A parent and its children can share resources
  - Children may share a subset of parent's resources
- Process in UNIX
  - a system call **fork()** system call creates a new process
  - a child process duplicates the memory of its parent

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### A Tree of Processes in Linux

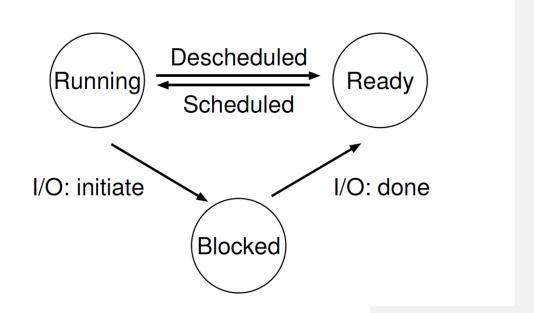


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## Life Cycle of a Process

- Running state
  - hold a CPU and execute instructions
- Ready state
  - can make a progress, but cannot hold a CPU
- Blocked state
  - cannot make a progress since it needs to wait for a certain condition (i.e., I/O)

 CPU scheduler makes a decision for process state transitions



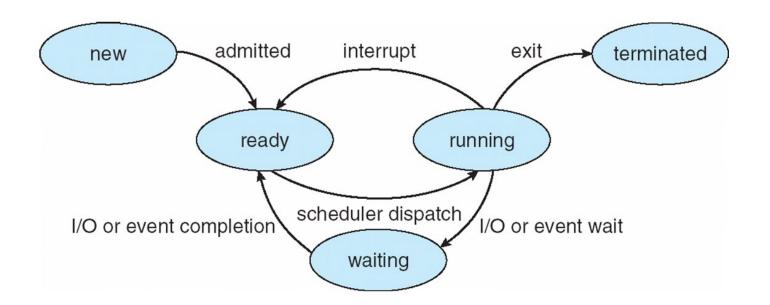
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## Another Representation of Process Life Cycle

- As a process executes, the process state changes
  - **new**: The process is being created
  - ready: The process is waiting to be assigned to a processor
  - running: Instructions are being executed
  - waiting: The process is waiting for some event to occur
  - terminated: The process has finished execution



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#### **Process Termination**

- Process executes last statement and then asks the operating system to delete it using the exit() system call
  - Returns status data from child to parent (via wait())
  - Process' resources are deallocated by operating system
- Parent may terminate the execution of children processes using the abort () system call. Some reasons for doing so:
  - Child has exceeded allocated resources
  - Task assigned to child is no longer required
  - The parent is terminating, and the operating systems does not allow a child to continue if its parent terminates

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# Example

Time	$\mathbf{Process}_0$	$\mathbf{Process}_1$	Notes
1	Running	Ready	
2	Running	Ready	
3	Running	Ready	
4	Running	Ready	Process <sub>0</sub> now done
5	_	Running	
6	_	Running	
7	_	Running	
8	_	Running	Process <sub>1</sub> now done

Time	$\mathbf{Process}_0$	$\mathbf{Process}_1$	Notes
1	Running	Ready	
2	Running	Ready	
3	Running	Ready	Process <sub>0</sub> initiates I/O
4	Blocked	Running	Process <sub>0</sub> is blocked,
5	Blocked	Running	so $Process_1$ runs
6	Blocked	Running	
7	Ready	Running	I/O done
8	Ready	Running	Process <sub>1</sub> now done
9	Running	_	
10	Running	_	Process <sub>0</sub> now done

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## Process Data Structure in Kernel: xv6 Example

- Called as Process Control Block
- Example of the xv6 kernel

```
// the information xv6 tracks about each process
// including its register context and state
struct proc {
                            // Start of process memory
 char *mem;
 uint sz;
                           // Size of process memory
 char *kstack;
                            // Bottom of kernel stack
                            // for this process
                            // Process state
 enum proc_state state;
 int pid;
                            // Process ID
 struct proc *parent;
                            // Parent process
                            // If !zero, sleeping on chan
 void *chan;
 int killed;
                            // If !zero, has been killed
 struct file *ofile[NOFILE]; // Open files
 struct inode *cwd; // Current directory
 struct context context;
                           // Switch here to run process
 struct trapframe *tf;
                            // Trap frame for the
                            // current interrupt
};
```

# Remainig Issues

- What's the overhead for virtualizing CPU?
- How to implement context switching?
- How to manage multiple processes?
- How a scheduler determines the next process to run?

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### Mechanisms for Process

- time-sharing
  - run one process for a while, and then switch to another one
  - issue
    - managing control
    - obtaining performance



- limited direct execution
  - run an application program directly on the CPU with some restriction
  - restriction
    - restricted memory accesses (H/W manipulation, resource allocation, etc.)
    - restricted instruction

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### Dual Mode Operation: User Mode & Kernel Mode

- Most contemporary processors provide dual mode operation
- User mode
  - for application program execution
  - restriction is enforced
    - a trap occurs when a process executes a restricted instruction under user mode
- Kernel model
  - for kernel execution
  - all privileged operations can be executed
- What if an application program needs to execute privileged operations?

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# System Call

- A way of an application program to call a kernel to get a system service
  - not possible to do this with the procedure call mechanism
- to execute a system call, a program must execute a trap instruction
  - the operation of a trap instruction
    - change the mode into the kernel mode
    - store the current PC at a kernel stack
    - jump to a predefined program location for handling the trap
      - trap table
      - trap handler
  - each system call is identified by its unique number (i.e. system-call number)

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## Example of System Call Workflow

OS @ run (kernel mode)	Hardware	Program (user mode)
Create entry for process list		
Allocate memory for program Load program into memory		
Setup user stack with argv		
Fill kernel stack with reg/PC return-from-trap		
	restore regs	
	(from kernel stack) move to user mode	
	jump to main	
		Run main()
		Call system call trap into OS
	save regs (to kernel stack)	
	move to kernel mode	
Handle trap	jump to trap handler	
Do work of syscall		
return-from-trap	wastawa wa sa	
	restore regs (from kernel stack)	
	move to user mode	
	jump to PC after trap	
		return from main
Free memory of process		trap (via exit ())
Remove from process list		

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## **Switching Between Processes**

 How can OS regain control of the CPU when it is given to an application program?

- Natural chance: blocked operation
- Periodic scheduling
  - -Cooperative approach
    - blocked operation
  - Preemptive scheduling approach
    - exploit a timer interrupt and its interrupt handler
    - requires HW support

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## **Preemptive Scheduling**

• scheduler: a kernel module that determines which process to dispatch at a chance (e.g., timer interrupt)

- context switch: a kernel module that is executed to switch processes running on a CPU
  - registered as a timer interrupt handler
  - steps
    - store the process status of a currently-running process to memory
      - CPU states
    - find the stored status of the next process from the memory
    - restore the stored status at the CPU
    - return the control back to the application program

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OS @ boot (kernel mode)	Hardware	
initialize trap table start interrupt timer	remember addresses of syscall handler timer handler start timer interrupt CPU in X ms	
OS @ run (kernel mode)	Hardware	Program (user mode)
Handle the trap Call switch() routine save regs(A) $\rightarrow$ proc_t(A) restore regs(B) $\leftarrow$ proc_t(B) switch to k-stack(B)	timer interrupt save regs(A) $\rightarrow$ k-stack(A) move to kernel mode jump to trap handler	Process A
return-from-trap (into B)	restore regs(B) $\leftarrow$ k-stack(B) move to user mode jump to B's PC	Process B

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### The xv6 Context Switch Code

```
# void swtch(struct context **old, struct context *new);
  # Save current register context in old
  # and then load register context from new.
   .qlobl swtch
   swtch:
     # Save old registers
     movl 4(%esp), %eax # put old ptr into eax
     popl 0(%eax) # save the old IP
     movl %esp, 4(%eax) # and stack
10
     movl %ebx, 8(%eax) # and other registers
11
     movl %ecx, 12(%eax)
12
     movl %edx, 16(%eax)
13
     movl %esi, 20(%eax)
14
     movl %edi, 24(%eax)
15
     movl %ebp, 28(%eax)
16
17
     # Load new registers
18
     movl 4(%esp), %eax # put new ptr into eax
     mov1 28(%eax), %ebp # restore other registers
     movl 24(%eax), %edi
     movl 20(%eax), %esi
     movl 16(%eax), %edx
     movl 12 (%eax), %ecx
     movl 8(%eax), %ebx
     movl 4(%eax), %esp # stack is switched here
     pushl 0(%eax) # return addr put in place
     ret
                        # finally return into new ctxt
```

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